



Missed a few lectures.

→ 5 - Mar

→ 9 - Mar

→ 11 - Mar

→ 12 - Mar

Added J's scanned notes right after this page. I apologize.

Order of the notes:

→ J's

→ Mine J sandwich j

→ J's

5/3/26

System of differential Equations :

$$y' = f(x, y) ; y(x_0) = y_0$$

$$y_1' = f_1(x, y_1, \dots, y_n)$$

$$y_2' = f_2(x, y_1, \dots, y_n)$$

$$\vdots$$
$$y_n' = f_n(x, y_1, \dots, y_n)$$

$$y = (y_1, \dots, y_n) \left. \begin{array}{l} \\ \\ \\ \end{array} \right\} n\text{-tuple}$$
$$f = (f_1, \dots, f_n)$$
$$y' = f(x, y)$$

Suppose $\phi_1, \phi_2, \dots, \phi_n$ exists, then $\phi_i' = f_i(x, \phi_1, \dots, \phi_n)$

Then, $\phi = (\phi_1, \dots, \phi_n)$ is a solⁿ of (1).

System of Linear DE :

$$y_1' = a_{11}y_1 + \dots + a_{1n}y_n + b_1(x)$$

$$y_2' = a_{21}y_1 + \dots + a_{2n}y_n + b_2(x)$$

\vdots

$$y_n' = a_{n1}y_1 + \dots + a_{nn}y_n + b_n(x)$$

$$\begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix}' = y' = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix} + \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix}$$

$$\boxed{y' = Ay + B(x)}$$

$B(x) = 0$ homogeneous

$B(x) \neq 0$ non-homogeneous.

$$A = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \dots & a_{nn} \end{pmatrix} \quad B = \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix} \quad y = \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix}$$

Ex: $y_1' = y_1 + 2y_2$
 $y_2' = 3y_1 + 4y_2$

$$\underline{\underline{\begin{pmatrix} y_1 \\ y_2 \end{pmatrix}' = \begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}}}$$

→ Suppose we have the n^{th} order ode, $(y)^{(n)} = f(x, y, \dots, y^{(n-1)})$, then $(\phi_1, \phi_2, \dots, \phi_{n-1})$ is the solⁿ.

→ Reduction of n^{th} order ode to a system of ode:

Consider transformation

$$\begin{array}{l} y_1 = y \\ y_2 = y' \\ y_3 = y'' \\ \vdots \\ y_{n-1} = y^{(n-2)} \\ y_n = y^{(n-1)} \end{array} \Rightarrow \begin{array}{l} y_1' = y_2 \\ y_2' = y_3 \\ y_3' = y_4 \\ \vdots \\ y_{n-1}' = y_n \\ y_n' = f(x, y_1, \dots, y_n) \end{array}$$

Consider the n^{th} order ode as $y^{(n)} + a_1 y^{(n-1)} + \dots + a_n y = b(x)$, $a_0(x) \neq 0$

$$y^{(n)} = \left(-\frac{a_1}{a_0}\right) y^{(n-1)} + \dots + \left(-\frac{a_n}{a_0}\right) y + \frac{b(x)}{a_0}$$

Consider the transformation

$$\begin{array}{l} y_1 = y \\ y_2 = y' \\ y_3 = y'' \\ \vdots \\ y_{n-1} = y^{(n-2)} \\ y_n = y^{(n-1)} \end{array} \Rightarrow \begin{array}{l} y_1' = y_2 = 0y_1 + 1y_2 + 0y_3 + \dots + 0y_n \\ y_2' = y_3 = 0y_1 + 0y_2 + 1y_3 + \dots + 0y_n \\ y_3' = y_4 = 0y_1 + \dots + 0y_3 + 1y_4 + \dots + 0y_n \\ \vdots \\ y_{n-1}' = y_n = 0y_1 + 0y_2 + \dots + 1y_n \\ y_n' = y^{(n)} = \left(-\frac{a_1}{a_0}\right) y_1 + \dots + \left(-\frac{a_{n-1}}{a_0}\right) y_{n-1} + \frac{b(x)}{a_0} \end{array}$$

$$\Rightarrow \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_n \end{pmatrix}' = \begin{pmatrix} 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 1 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \dots & 1 \\ -\frac{a_1}{a_0} & -\frac{a_2}{a_0} & -\frac{a_3}{a_0} & \dots & -\frac{a_{n-1}}{a_0} \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \\ \vdots \\ y_{n-1} \\ y_n \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \\ \vdots \\ 0 \\ b(x)/a_0 \end{pmatrix}$$

$$\underline{\underline{\Rightarrow y' = Ay + B}}$$

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Recap? $y^{(n)} = f(x, y, y', \dots, y^{(n-1)})$

$y(x_0) = a_0, y'(x_0) = a_1, \dots, y^{(n-1)}(x_0) = a_{n-1}$

$\Phi(x_0) = (a_0, a_1, \dots, a_{n-1})$

Q1) Find the matrix form of following de.

$y''' - 4y'' + 10y' - 6y = 9x$

$y_1 = y \quad y_1' = y' = y_2$

$y_2 = y' \Rightarrow y_2' = y'' = y_3$

$y_3 = y'' \Rightarrow y_3' = y''' = 4y'' - 10y' + 6y + 9x$

$y_3' = 4y_3 - 10y_2 + 6y_1 + 9x$

$\Rightarrow y_1' = 0y_1 + 1y_2 + 0y_3$

$y_2' = 0y_1 + 0y_2 + 1y_3$

$y_3' = 6y_1 - 10y_2 + 4y_3 + 9x$

$\Rightarrow \begin{pmatrix} y_1' \\ y_2' \\ y_3' \end{pmatrix} = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 6 & -10 & 4 \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix} + \begin{pmatrix} 0 \\ 0 \\ 9x \end{pmatrix}$

$\Rightarrow y' = Ay + B$

Existence and Uniqueness of the system of DE:

Thm: Let $A(x)$ be a continuous $n \times n$ matrix defined on a closed and bounded interval I .
 [Existence implied by uniqueness] Then, the IVP, $y' = A(x)y(x)$ $\{ \textcircled{1} \}$ has a unique solⁿ on I .
 $y(x_0) = y_0, \quad x_0 \in I$

Pf: First we note that solving $\textcircled{1}$ is equivalent to solving integral eqⁿ,

$y(x) = y_0 + \int_{x_0}^x A(t)y(t) dt$
 $y(x_0) = y_0$

Here $\text{norm}(A) := |A| = \sum |a_{ij}|$
 $A' = (a_{ij})'$

Consider the approximation,

$y_{n+1}(x) = y_0 + \int_{x_0}^x A(t)y_n(t) dt$

We will prove that $y_n(x)$ conv unif to $y(x)$.

→ First we claim that $\{y_n\}$ is a Cauchy seq.,

we note that y_n is n^{th} partial sum of the series,
 $y_0 + \sum_{i=1}^n (y_{i+1} - y_i)$

Consider $y_1(x) - y_0 = \int_{x_0}^x A(t) y_0(t) dt$

$$|y_1 - y_0| \leq \int_{x_0}^x |A(t)| |y_0| dt$$

$$\leq M |y_0| \int_{x_0}^x dt$$

$$= M |y_0| (x - x_0)$$

$$|y_2 - y_1| = \left| \int_{x_0}^x A(t) (y_1 - y_0) dt \right|$$

$$\leq M \int_{x_0}^x |y_1 - y_0| dt$$

$$\leq M^2 \frac{|y_0| (x - x_0)^2}{2}$$

$$\dots |y_{n+1} - y_n| \leq \frac{M^{n+1} |y_0| (x - x_0)^{n+1}}{(n+1)!} \rightarrow (2)$$

- RHS of (2) is the $(n-2)^{th}$ term of sum $\frac{\sum_{i=0}^{\infty} M^{n+1} |y_0| (x - x_0)^{n+1}}{(n+1)!}$ which is a geometric series

series $|y_0| e^{M(x-x_0)}$.

- Here, $\{y_n\}$ is a Cauchy sequence in \mathbb{R}^n . Since \mathbb{R}^n is complete, $\{y_n\}$ converges uniformly & norm convergence is unif. Thus, $\{y_n\}$ converges uniformly to $y(x)$.

→ Claim: Solⁿ is unique,

Let y_1, y_2 be two solutions of (1).

$$y_1(x) = y_0 + \int_{x_0}^x A(t) y_1(t) dt$$

$$y_2(x) = y_0 + \int_{x_0}^x A(t) y_2(t) dt$$

$$|y_1(x) - y_2(x)| \leq M \int_{x_0}^x |y_1(t) - y_2(t)| dt$$

- By Gronwall's inequality, $y_1 = y_2$,

$$|y_1 - y_2| \leq M \int_{x_0}^x |y_1 - y_2| dt \leq \epsilon + M \int_{x_0}^x |y_1(t) - y_2(t)| dt \text{ for } \epsilon > 0$$

$$\text{Let } w(x) = |y_1 - y_2|$$

$$w(x) = \epsilon + M \int_{x_0}^x w(t) dt$$

$$w(x_0) = \epsilon$$

$$w'(x) = M w(x) \leq M w(x) \quad (\because w(x) \leq \epsilon(x))$$

$$w' - M w \leq 0$$

1st order ineq., solving it we get,

$$w(x) e^{-Mx} - w(x_0) e^{-Mx_0} \leq 0$$

$$w(x) = w(x_0) e^{M(x-x_0)} \leq \epsilon e^{M(x-x_0)}$$

$$w(x) \leq 0$$

$$\Rightarrow |y_1 - y_2| \leq 0$$

< 0 not possible

$$\Rightarrow |y_1 - y_2| = 0$$

$$\Rightarrow y_1 = y_2 \quad \text{sol}^n \text{ unique}$$

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Proof:

Existence & uniqueness: $y' = A(x)y$, $y(x_0) = y_0$ ①

set of solⁿ ϕ_1, \dots, ϕ_n form a vector space of dim n .

$$\text{set } \phi_1 = \begin{bmatrix} \phi_{11} \\ \phi_{21} \\ \vdots \\ \phi_{n1} \end{bmatrix} \dots \phi_n = \begin{bmatrix} \phi_{1n} \\ \phi_{2n} \\ \vdots \\ \phi_{nn} \end{bmatrix}$$

$$\phi = (\phi_1, \phi_2, \dots, \phi_n)$$

If ϕ_1, \dots, ϕ_n are l.i., then the solⁿ is called Fundamental Matrix Solⁿ.
[Fundamental Set of solⁿ]

If ϕ_1, \dots, ϕ_n are solⁿ of $y' = A(x)y$, then Wronskian of solⁿ $W(\phi_1, \dots, \phi_n)$ is equal to

$$\begin{vmatrix} \phi_{11} & \dots & \phi_{1n} \\ \phi_{21} & \dots & \phi_{2n} \\ \vdots & & \vdots \\ \phi_{n1} & \dots & \phi_{nn} \end{vmatrix}$$

Ex: Find the fundamental matrix solⁿ of $\begin{pmatrix} y_1 \\ y_2 \end{pmatrix}' = \begin{pmatrix} x & 0 \\ 0 & 2x \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}$

$$y_1' = xy_1$$

$$y_2' = 2xy_2$$

$$y_1' = xy_1 \Rightarrow y_1'/y_1 = x \Rightarrow y_1 = c_1 e^{x^2/2}$$

$$y_2' = 2xy_2 \Rightarrow y_2'/y_2 = 2x \Rightarrow y_2 = c_2 e^{x^2}$$

$$y_1 = \begin{pmatrix} e^{x^2/2} \\ 0 \end{pmatrix} \quad y_2 = \begin{pmatrix} 0 \\ e^{x^2} \end{pmatrix}$$

$$\phi = \begin{bmatrix} e^{x^2/2} & 0 \\ 0 & e^{x^2} \end{bmatrix}$$

Are y_1, y_2 l.i., ϕ_1, ϕ_2 are l.i. $\Leftrightarrow W(\phi_1, \phi_2) \neq 0$

Ex: $y' = Ay$ $y = \begin{pmatrix} y_1 \\ y_2 \\ y_3 \end{pmatrix}$ $A = \begin{pmatrix} -x & x & 0 \\ 0 & -x & 0 \\ 0 & 0 & x \end{pmatrix}$

$$y_2' = -xy_2 \Rightarrow y_2'/y_2 = -x \Rightarrow y_2 = c_2 e^{-x^2/2}$$

$$y_1' = -xy_1 + xy_2$$

$$y_3' = xy_3 \Rightarrow y_3'/y_3 = x \Rightarrow y_3 = c_3 e^{x^2/2}$$

$$y_1' = -xy_1 + cxe^{-x/2}$$

$$y_1' + xy_1 = ce^{-x/2}$$

$$p = x \Rightarrow A' = p = x$$

$$\Rightarrow A = x^2/2$$

$$y_1 = e^{-A(x)} \int e^{A(t)} Q(t) dt + ce^{-A(x)}$$

$$= e^{-x^2/2} \int e^{t^2/2} te^{-t^2/2} dt + ce^{-x^2/2}$$

$$= e^{-x^2/2} \frac{x^2}{2} + ce^{-x^2/2}$$

$$= e^{-x^2/2} \left(\frac{x^2}{2} + c \right)$$

Ex: After finding M , compute the first two successive approx^s of system.

$$\begin{pmatrix} y_1 \\ y_2 \end{pmatrix}' = \begin{pmatrix} \sin x & 0 \\ 0 & \cos x \end{pmatrix} \begin{pmatrix} y_1 \\ y_2 \end{pmatrix}$$

$$\begin{pmatrix} y_1(0) \\ y_2(0) \end{pmatrix} = \begin{pmatrix} 0 \\ 1 \end{pmatrix} \text{ and } I = [0, \pi]$$

$$M \rightarrow \text{norm bound} \Rightarrow \left\| \begin{pmatrix} \sin x & 0 \\ 0 & \cos x \end{pmatrix} \right\| \leq 2 \quad (2)$$

$$y_n(x) = y_0 + \int_{x_0}^x A(t) y_{n-1}(t) dt$$

$$y_0 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$y_1 = y_0 + \int_{x_0}^x \begin{pmatrix} \sin t & 0 \\ 0 & \cos t \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} dt = y_0 + \int_{x_0}^x \begin{pmatrix} 0 \\ \cos t \end{pmatrix} dt$$

$$= \begin{pmatrix} 0 \\ 1 \end{pmatrix} + \begin{pmatrix} 0 \\ \sin(x) \end{pmatrix} = \begin{pmatrix} 0 \\ 1 + \sin x \end{pmatrix}$$

$$y_2 = y_0 + \int_{x_0}^x \begin{pmatrix} \sin t & 0 \\ 0 & \cos t \end{pmatrix} \begin{pmatrix} 0 \\ 1 + \sin t \end{pmatrix} dt = \begin{pmatrix} 0 \\ 1 \end{pmatrix} + \int_0^x \begin{pmatrix} 0 \\ \cos t(1 + \sin t) \end{pmatrix} dt = \begin{pmatrix} 0 \\ 1 + \frac{(1 + \sin x)^2 - 1}{2} \end{pmatrix}$$

$$= \begin{pmatrix} 0 \\ \frac{(1 + \sin x)^2 + 1}{2} \end{pmatrix}$$

→ Thm: Let $A(x)$ be an $n \times n$ matrix on I & let ϕ satisfy $y' = A(x)y$. Then, $\det(\phi)$ satisfies the first order eqⁿ $(\det(\phi))' = \text{tr}(A)\det(\phi)$.
Equivalently, $\det(\phi(x)) = \det(\phi(x_0))e^{\int_{x_0}^x \text{tr}(A(t))dt}$ → (Abel's formula).

Proof: Given that ϕ satisfies the eqⁿ $y' = Ay$

$$\Rightarrow \phi' = A\phi$$

$$\Rightarrow \phi'_{ij} = \sum_{k=1}^n a_{ik} \phi_{kj} \quad i, j = 1, \dots, n$$

$$\text{Let } \phi = \begin{pmatrix} \phi_{11} & \dots & \phi_{1n} \\ \phi_{21} & \dots & \phi_{2n} \\ \vdots & \dots & \vdots \\ \phi_{m1} & \dots & \phi_{mn} \end{pmatrix}, \det(\phi) = \begin{vmatrix} \phi_{11} & \dots & \phi_{1n} \\ \phi_{21} & \dots & \phi_{2n} \\ \vdots & \dots & \vdots \\ \phi_{m1} & \dots & \phi_{mn} \end{vmatrix}$$

$$(\det(\phi))' = \begin{vmatrix} \phi'_{11} & \phi'_{12} & \dots & \phi'_{1n} \\ \phi_{21} & \phi_{22} & \dots & \phi_{2n} \\ \vdots & \vdots & \dots & \vdots \\ \phi_{m1} & \phi_{m2} & \dots & \phi_{mn} \end{vmatrix} + \dots + \begin{vmatrix} \phi_{11} & \phi_{12} & \dots & \phi_{1n} \\ \phi_{21} & \phi_{22} & \dots & \phi_{2n} \\ \vdots & \vdots & \dots & \vdots \\ \phi'_{m1} & \phi'_{m2} & \dots & \phi'_{mn} \end{vmatrix}$$

Consider first term, $\begin{vmatrix} \phi_{11} & \phi_{12} & \dots & \phi_{1n} \\ \phi_{21} & \phi_{22} & \dots & \phi_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ \phi_{n1} & \phi_{n2} & \dots & \phi_{nn} \end{vmatrix} = \begin{vmatrix} \sum a_{1k} \phi_{k1} & \sum a_{1k} \phi_{k2} & \dots & \sum a_{1k} \phi_{kn} \\ \phi_{21} & \phi_{22} & \dots & \phi_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ \phi_{n1} & \phi_{n2} & \dots & \phi_{nn} \end{vmatrix} = \begin{vmatrix} a_{11} \phi_{11} & a_{11} \phi_{12} & \dots & a_{11} \phi_{1n} \\ \phi_{21} & \phi_{22} & \dots & \phi_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ \phi_{n1} & \phi_{n2} & \dots & \phi_{nn} \end{vmatrix} + 0$

$= a_{11} \det \phi$

Continuing like,

$(\det(\phi))' = (a_{11} + a_{22} + \dots + a_{nn}) \det(\phi) = \text{tr}(A) \det \phi$

$\Rightarrow \frac{(\det(\phi))'}{\det \phi} = \text{tr}(A) \Rightarrow \det \phi(x) = \det(\phi(x_0)) e^{\int_{x_0}^x \text{tr}(A(t)) dt}$

12/8/26

Thm: A solution matrix ϕ of the matrix diff eqn $y' = A(x)y$, $x \in I$, is a fundamental matrix $n \times n \iff \det(\phi) \neq 0$ for any $x \in I \rightarrow \text{①}$

pf (\Rightarrow): Suppose ϕ be a FMS. Then, wkt the components of ϕ , namely $\phi_1, \phi_2, \dots, \phi_n$ forms a basis of the solution space.

Let ψ be any solution of ①. Since $\{\phi_i\}$ is a basis, then $\exists ! c_i$'s s.t. $\psi(x) = \sum c_i \phi_i(x)$

$\Rightarrow \psi_i(x) = \sum \phi_{ij} c_j, i=1, \dots, n$

This is a sys of n linear eqns.

Since this sys has non-trivial solution for any fixed $x_0 \in I$, we have

$\det(\phi(x_0)) \neq 0$
 $\Rightarrow \det(\phi(x)) \neq 0$ (from last thm)

(\Leftarrow) Conversely, suppose $\det(\phi(x)) \neq 0$

$\Rightarrow \omega(\phi_1, \dots, \phi_n)(x) \neq 0$

$\Rightarrow \phi_1, \dots, \phi_n$ are L.I.

$\Rightarrow \phi = (\phi_1, \dots, \phi_n)$ is a FMS ②

Thm: If ϕ is a FMS of $y' = A(x)y$ & C is any const non-singular matrix, then ϕC is a FMS

(i) Every soln of the system is of this type for some non-singular matrix

pf (i) Given that ϕ is FMS of $y' = A(x)y$

$\Rightarrow \det(\phi) \neq 0$ (from thm)

$\Rightarrow \phi$ is non-singular.

wkt, C is also non-singular

$\Rightarrow \phi C$ is non-singular.

$\Rightarrow \det(\phi C) \neq 0$

$\Rightarrow \underline{\underline{\phi C}}$ is FMS (pd)

(ii) Let ϕ_1 and ϕ_2 be the FM of $y' = A(x)y$.

Let $\phi_2 = \phi_1 \psi$.

We claim that ψ is non-singular constt matrix

$$\phi_2 = \phi_1 \psi$$

$$\Rightarrow \phi_2' = \phi_1' \psi + \phi_1 \psi'$$

$$\Rightarrow A \phi_2 = A \phi_1 \psi + \phi_1 \psi'$$

$$\Rightarrow A \phi_2 = A \phi_2 + \phi_1 \psi'$$

$$\Rightarrow \phi_1 \psi' = 0 \Rightarrow \psi' = 0$$

$$\Rightarrow \psi = c$$

$$\therefore \phi_2 = \phi_1 c \Rightarrow c = \phi_1^{-1} \phi_2 \quad \text{(pd)}$$

→ Show: Let A be a constt matrix and ϕ be the FM of the sys $y' = Ay$ at $\phi(0) = I$, the identity matrix. Show, ϕ satisfies $\boxed{\phi(x+t) = \phi(x)\phi(t) \quad \forall x, t \in I}$

Prf: Let us denote $Y(x) = \phi(x+t)$
 $Z(x) = \phi(x)\phi(t)$

$$\text{IPT } Y(x) = Z(x)$$

We claim that Y & Z are sol^{ns} of $y' = Ay$ with same initial condⁿ.

$$\text{Consider } Y'(x) = \phi'(x+t) = A \phi(x+t) = AY(x)$$

$$Y(0) = \phi(t)$$

$$\text{Consider } Z'(x) = \phi'(x)\phi(t) = A \phi(x)\phi(t) = AZ(x)$$

$$Z(0) = \phi(0)\phi(t) = I\phi(t) = \phi(t)$$

Then, Y and Z are sol^{ns} of $y' = Ay$ with same initial condⁿ $Y(0) = Z(0) = \phi(t)$.

Here by Existence & Uniqueness thm, $Y = Z$

$$\Rightarrow \underline{\underline{\phi(x+t) = \phi(x)\phi(t)}} \quad \text{(pd)}$$

→ Solution of System of Non-homogeneous Eq^{ns}

We have $y' = A(x)y + B(x)$ $B(x) \neq 0$.

→ Show: Let ϕ_0 be any solⁿ of non-homogeneous sys $y' = A(x)y + B(x) \rightarrow \textcircled{1}$
 and $\phi_1, \phi_2, \dots, \phi_n$ be a basis of sol^{ns} of the hom. sys $y' = A(x)y \rightarrow \textcircled{2}$
 and let c_1, \dots, c_n be constts. Show,

(i) the vector function $\phi_0 + \sum_{i=1}^n c_i \phi_i$ is also a solⁿ of sys $\textcircled{1}$ for every choice of c_i 's. $\rightarrow \textcircled{3}$

(ii) Any arbitrary solⁿ of (1) is of form (5) for suitable choice of c_i's.

Pf: Given that ϕ_0 is a solⁿ of the non-hom syst $y' = A(x)y + B(x)$
(1)

$$\Rightarrow \phi_0' = A\phi_0 + B$$

Also, we have ϕ_1, \dots, ϕ_n is a basis of solⁿ of $y' = Ay$.

$$\Rightarrow \sum c_i \phi_i \text{ is also a solⁿ of } y' = A(x)y$$

$$\Rightarrow (\sum c_i \phi_i)' = A \sum c_i \phi_i$$

Consider $(\phi_0 + \sum c_i \phi_i)' = \phi_0' + (\sum c_i \phi_i)'$
 $= A\phi_0 + B + A \sum c_i \phi_i$

$$= A(\phi_0 + \sum c_i \phi_i) + B$$

$$\Rightarrow \underline{\underline{\phi_0 + \sum c_i \phi_i}} \text{ is a solⁿ of (1) } \checkmark$$

(iii) Let ϕ be any solⁿ of (1)

Claim that $\phi - \phi_0$ is a solⁿ of (2)

consider $(\phi - \phi_0)' = \phi' - \phi_0'$
 $= A\phi + B - (A\phi_0 + B)$
 $= A(\phi - \phi_0)$

$$\Rightarrow \phi - \phi_0 \text{ is a solⁿ of (2)}$$

Since ϕ_1, \dots, ϕ_n is a basis of solⁿ-space of (2)

$$\phi - \phi_0 = \sum c_i \phi_i \text{ for some } c_i$$

$$\Rightarrow \underline{\underline{\phi = \phi_0 + \sum c_i \phi_i}} \quad \text{Q.E.D.}$$

Lect - 4, Mar 16

Particular soln of a non-homog. system using variation of parameter technique

Theorem:

If $\phi(x)$ is the FM of the homogenous system $y' = A(x)y$, $x \in I$, Then ψ defined by

$$\psi(x) = \phi(x) \int_{x_0}^x \phi^{-1}(t) \cdot B(t) \cdot dt$$

is a solution of IVP of the non-homogenous system, $y' = A(x)y + B(x)$, $y(x_0) = 0$

Proof:

Given that ϕ is a FM of

$$y' = A(x)y \quad \text{--- ①}$$

Let us assume that,

$$\psi = \phi u$$

$$\text{is a solution of } y' = Ay + B \quad \text{--- ②}$$

ψ is a solution of ②.

$$\Rightarrow \psi' = A\psi + B$$

$$\psi = A\phi u + B \quad \text{--- ③}$$

But $\psi' = (\phi u)'$

$$= \phi' u + \phi u' \quad \text{--- ④}$$

From ③ and ④,

$$A\phi u + B = A\phi u + \phi u'$$

$$\Rightarrow B = \phi u'$$

$$\Rightarrow u' = \phi^{-1} \cdot B$$

$$\Rightarrow u(x) = \int_{x_0}^x \phi^{-1}(t) \cdot B(t) \cdot dt$$

$$\Rightarrow \psi(x) = \phi(x) \cdot \int_{x_0}^x \phi^{-1}(t) \cdot B(t) \cdot dt \quad \text{--- ⑤}$$

On the other hand, if ψ is of the form ⑤, then ψ satisfies the equation ⑤.

Question:

Obtain the soln $\psi(x)$ of the IVP,

$$y' = Ay + B \quad \text{where}$$

$$y = \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}, \quad A = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix}, \quad B = \begin{bmatrix} \sin ax \\ \cos bx \end{bmatrix}$$

$$\psi(x_0) = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

Solution:

Step 1: Find the FM ϕ .

Consider,

$$y' = Ay$$

$$\begin{bmatrix} y_1 \\ y_2 \end{bmatrix}' = \begin{bmatrix} 1 & 0 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix}$$

$$\Rightarrow \begin{aligned} y_1' &= y_1, & y_1 &= e^x \\ y_2' &= 2y_2, & y_2 &= e^{2x} \end{aligned}$$

\therefore the FM,

$$\phi = \begin{bmatrix} e^x & 0 \\ 0 & e^{2x} \end{bmatrix}$$

Step 2:

to find the solution ψ , first we compute ϕ^{-1} .

$$\phi^{-1} = \begin{bmatrix} e^{-x} & 0 \\ 0 & e^{-2x} \end{bmatrix}$$

We have,

$$\begin{aligned} \psi &= \phi \cdot \int_{x_0}^x \phi^{-1}(t) \cdot B(t) \cdot dt \\ &= \phi \int_{x_0}^x \begin{bmatrix} e^{-t} & 0 \\ 0 & e^{-2t} \end{bmatrix} \begin{bmatrix} \sin at \\ \cos bt \end{bmatrix} dt \\ &= \phi \int_0^x \begin{bmatrix} e^{-t} \cdot \sin at \\ e^{-2t} \cdot \cos bt \end{bmatrix} dt \end{aligned}$$

To note:

$$\int e^{ax} \cdot \cos bx = \frac{e^{ax}}{a^2 + b^2} (a \cos bx + b \sin bx) + C_1$$

$$\int e^{ax} \cdot \sin bx = \frac{e^{ax}}{a^2 + b^2} (a \sin bx - b \cos bx) + C_2$$

$$\psi(x) = \begin{bmatrix} e^x & 0 \\ 0 & e^{2x} \end{bmatrix} \begin{bmatrix} \frac{e^{-x}}{1+a^2} (-\sin ax - a \cos ax) + C_1 \\ \frac{e^{-2x}}{4+a^2} (-2 \cos ax - a \sin ax) + C_2 \end{bmatrix}$$

$$\psi(0) = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \Rightarrow C_1 = \frac{a}{1+a^2}, C_2 = \frac{6+b^2}{4+b^2}$$

$$\psi(x) = \begin{bmatrix} \frac{1}{1+a^2} (ae^x - (\sin ax - a \cos ax)) \\ \frac{1}{4+b^2} ((6+b^2)e^{2x} + b \sin bx - 2 \cos bx) \end{bmatrix}$$

Linear system with constant coefficients

Theorem:

The general solution of $y' = Ay$ ——— ①

where A is a constant matrix, is

$$y(x) = e^{xA} \cdot c \quad \text{where } c \text{ is}$$

arbitrary constant column vector.

② If ① satisfies the initial condition $y(x_0) = y_0$ then the solution is $y(x) = e^{(x-x_0)A} \cdot y_0$.

③ The FM of ① is $\phi(x) = e^{xA}$.

Proof:

Consider $y' = Ay$ ——— ①

$\Rightarrow 0 = y' - Ay$ ——— ②

let $u(x) = e^{-xA} \cdot y(x)$.

Then,

$$u'(x) = -A e^{-xA} \cdot y + e^{-xA} \cdot y' = (y' - Ay) \cdot e^{-xA}$$

$\therefore u' = 0$

$$\Rightarrow u = c$$

$$\Rightarrow e^{-xA} y = c$$

$$y = c \cdot e^{xA} \quad \text{————— ②}$$

② We have $y(x) = e^{xA} c$

$$\Rightarrow y(x_0) = e^{x_0 A} c$$

$$y_0 = e^{x_0 A} c$$

$$c = e^{-x_0 A} \cdot y_0$$

$$\Rightarrow y(x) = e^{xA} \cdot e^{-x_0 A} \cdot y_0$$

$$y(x) = e^{A(x-x_0)} \cdot y_0$$

③ Let $\phi = e^{xA}$

$$\therefore \phi' = A e^{xA} = A \phi$$

$\Rightarrow \phi$ is a soln of $y' = Ay$.

Consider

$$\det(\phi) = \det(\phi(x_0)) e^{\int_{x_0}^x \text{tr}(A) \cdot dt}$$

\nearrow trace(A)

$$= \det(e^{x_0 A}) e^{\text{tr}(A) \cdot (x-x_0)} \neq 0$$

$\Rightarrow \phi$ is a FM.

Note:

$$e^{xA} = I + xA + \frac{x^2}{2!} A^2 + \dots$$

For eg,

suppose $A = \begin{bmatrix} a_1 & 0 \\ 0 & a_2 \end{bmatrix}$

\therefore

$$e^{xA} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + x \begin{bmatrix} a_1 & 0 \\ 0 & a_2 \end{bmatrix} + \frac{x^2}{2} \begin{bmatrix} a_1^2 & 0 \\ 0 & a_2^2 \end{bmatrix}$$

$$= \begin{bmatrix} 1 + xa_1 + \frac{x^2}{2} a_1^2 + \dots & 0 \\ 0 & 1 + xa_2 + \frac{x^2}{2} a_2^2 + \dots \end{bmatrix}$$

Eigenvalue or Eigen vector method to compute 'n' independent solns.

Theorem:

consider a vector differential eqn,

$$y' = Ay(x), \quad x \in I \quad \text{--- ①}$$

where A is an nxn constant matrix.

i) If $\lambda_1, \lambda_2, \lambda_3, \dots, \lambda_n$ are real distinct eigenvalue of A and v_1, v_2, \dots, v_n are the corresponding eigenvectors of A, then $e^{\lambda_1 x} v_1, e^{\lambda_2 x} v_2, \dots, e^{\lambda_n x} v_n$ for LI soln of ① and the gen. soln of ① is

$$y(x) = \sum c_i e^{\lambda_i x} v_i, \quad c_i \text{'s are const.}$$

ii) If $\lambda_1, \lambda_2, \dots, \lambda_m, m < n$ are eigenvalues of A with multiplicity n_1, n_2, \dots, n_m , where

$$n_1 + n_2 + \dots + n_m = n$$

with the corresponding eigenvalue, then the soln is given by,

$$y(x) = e^{xA} \sum c_i = \sum e^{\lambda_i x} \left[\sum_{j=0}^{n_i-1} \frac{x^j}{j!} (A - \lambda_i E)^j \right] c_i$$

where $y(0) = C = (c_1, c_2, \dots, c_n)$

Proof:

Given that $y' = Ay$, $A_{n \times n}$ matrix.

$$\text{--- ①}$$

let us assume that $y(x) = e^{\lambda x} v$ is a soln of ①. v is a non-zero constant vector.

Then, $y' = \lambda e^{\lambda x} v$

$$\therefore y' = Ay \Rightarrow \lambda e^{\lambda x} v = A e^{\lambda x} v$$

$$\Rightarrow (A - \lambda E) e^{\lambda x} v = 0$$

$$(A - \lambda E) v = 0$$

$$|A - \lambda E| = 0 \quad \text{--- ②}$$

Then the charac. eq. and has n roots.

Case 1:

If $\lambda_1, \lambda_2, \dots, \lambda_n$ are distinct roots of ②, then we have n LI eigenvalues, v_1, \dots, v_n and have,

$$e^{\lambda_1 x} v_1, \dots, e^{\lambda_n x} v_n \text{ are n LI soln}$$

of the system ①.

thus the general soln is $y(x) = \sum c_i e^{\lambda_i x} v_i$

Case 2:

Suppose $\lambda_1, \lambda_2, \dots, \lambda_m$ are eigenvalue of ② with multiplied n_1, n_2, \dots, n_m such that $n = n_1 + n_2 + \dots + n_m$.

If λ_i is an eigenvalue with multiplicity n_i , then $(A - \lambda_i E)^{n_i} v = 0$

let $X_i \subseteq \mathbb{R}^n$ be the subspace spanned by the eigenvector v_i .

Then we have,

$$\mathbb{R}^n = X_1 \oplus X_2 \oplus \dots \oplus X_m$$

Any $c \in \mathbb{R}^n$, $c = c_1 + c_2 + \dots + c_m$, $c_i \in X_i$.

we know that

$$y(x) = e^{xA} c \text{ is a soln of ①, } c \in \mathbb{R}^n \\ = e^{xA} \sum c_i \\ = \sum_{i=1}^m e^{xA} c_i$$

$$e^{xA} = e^{\lambda_i x} e^{(A - \lambda_i E)x} \\ e^{(A - \lambda_i E)x} = E + x(A - \lambda_i E) + \frac{x^2}{2!} (A - \lambda_i E)^2 + \dots$$

$$e^{xA} c_i = e^{\lambda_i x} \left[E + x(A - \lambda_i E) + \dots \right] c_i$$

But we know that

$$(A - \lambda_i E)^i v = 0, \quad i \geq n_i$$
$$e^{xA} \cdot c_i = e^{\lambda_i x} \left[\sum_{j=0}^{n_i-1} \frac{x^j}{j!} (A - \lambda_i E)^j \right] c_i$$

$$\Rightarrow y(x) = \sum_{i=1}^m e^{x A} \cdot c_i$$
$$= \sum_{i=1}^m e^{\lambda_i x} \left[\dots \dots \dots \right] c_i$$

Algorithm for computing the soln of $y' = Ay$.

Step 1:

Compute the eigenvalue of A .

Step 2:

Case 1: If λ_i 's are distinct, then

$$e^{\lambda_i x} v_i, \quad i=1, \dots, n \quad \text{where}$$

v_i 's are the eigen vectors, are the soln of $y' = Ay$.

Case 2: Suppose the eigenvalue have

multiplicity,

for example, multiplicity 2.

The second LI soln is $e^{\lambda x} [v + (A - \lambda E)v]$

$$(A - \lambda E)^2 v = 0$$

but, $(A - \lambda E)v \neq 0$

This process can be repeated for all other eigen values.

Problem:

$$y' = Ay$$

$$A = \begin{bmatrix} 5 & 4 \\ 1 & 2 \end{bmatrix}$$

Solution:

Step 1: To find the eigen value.

Consider

$$(A - \lambda I) = 0$$

$$\begin{vmatrix} 5-\lambda & 4 \\ 1 & 2-\lambda \end{vmatrix} = 0$$

$$(5-\lambda)(2-\lambda) - 4 = 0$$

$$\Rightarrow \lambda = 1, 6.$$

Step 2:

To find the eigen vectors,

when $\lambda = 1$

$$\text{Consider } (A - \lambda I)v = 0$$

$$\Rightarrow \begin{bmatrix} 5-1 & 4 \\ 1 & 2-1 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\Rightarrow v_1 + v_2 = 0 = (1, -1)$$

$$v = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$

When $\lambda = 6$,

$$\begin{bmatrix} 5-6 & 4 \\ 1 & 2-6 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} -1 & 4 \\ 1 & -4 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$v_1 = 4, \quad v_2 = 1$$

$$v = \begin{bmatrix} 4 \\ 1 \end{bmatrix}$$

Problems:

1. $y' = Ay$.

$$A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 2 \end{bmatrix}$$

2. Determine e^{xA} and FM of $y' = Ay$.

$$A = \begin{bmatrix} -1 & 2 & 3 \\ 0 & -2 & 1 \\ 0 & 3 & 0 \end{bmatrix}$$

Linear system with periodic coefficients

We say that solution $y(x)$ of $y' = A(x) \cdot y$ is periodic with period ω , if $y(x + \omega) = y(x)$.

If the matrix $A(x)$ is said to be of period ω , if $A(x + \omega) = A(x)$.

Theorem:

The system $y' = A(x) \cdot y$ admits non-zero periodic solution of period ω .

$\Leftrightarrow E \cdot e^{A\omega}$ is singular,
when E is default matrix.

Proof:

We know that the solution of $y' = A(x) \cdot y$ is $y(x) = e^{xA} \cdot c$, $c \neq 0$.

y is periodic iff $y(x + \omega) = y(x)$

$\Leftrightarrow e^{(x+\omega)A} \cdot c = e^{xA} \cdot c$

$\Leftrightarrow e^{xA} \cdot e^{\omega A} \cdot c = e^{xA} \cdot c$

$e^{xA} (E - e^{\omega A}) \cdot c = 0$
 $\underbrace{\hspace{10em}}_{=0}$

$\det(E - e^{\omega A}) = 0$

$E - e^{\omega A}$ is singular.

Theorem:

Let the matrix $A(x)$ and the function $B(x)$ be continuous and periodic with $\omega \in \mathbb{R}$. Then the differential system,

$y' = A(x) \cdot y + B(x) \quad \text{--- } \textcircled{1}$

has a periodic solution.

$y(x)$ of period $\omega \iff y(0) = y(\omega)$

Proof:

Suppose $\textcircled{1}$ has a periodic solution $y(x)$

$\Rightarrow y(x + \omega) = y(x)$

$\Rightarrow y(\omega) = y(0)$.

Conversely suppose $\textcircled{1}$ has a soln $y(x)$ s.t.

$y(0) = y(\omega)$. Then we need to prove that y is periodic, i.e. to prove that,

$y(x + \omega) = y(x)$.

Let $v(x) = y(x + \omega)$

Claim v is a soln.

$v'(x) = y'(x + \omega) = A(x + \omega) \cdot y(x + \omega) + B(x + \omega)$
 $= A(x) \cdot v(x) + B(x)$

$\Rightarrow v$ is a soln.

and $v(0) = y(\omega) = y(0)$

$\Rightarrow v(x) = y(x) \quad \left\{ \begin{array}{l} \because \text{uniqueness of} \\ \text{soln} \end{array} \right.$

$\Rightarrow y(x + \omega) = y(x)$

$\Leftrightarrow (E - e^{\omega A})c = 0$, thus have a non-trivial soln,
 $\det(E - e^{\omega A}) = 0$

$\Rightarrow E - e^{\omega A}$ is singular.

Theorem:

Let the matrix $A(x)$ be continuous and periodic with period ω . Further let $\phi(x)$ be a FM of the differential system,

$y' = A(x) \cdot y \quad \text{--- } \textcircled{1}$

Then $\textcircled{1}$ has a non-trivial periodic solution $y(x)$ of period $\omega \iff \det(\phi(\omega) - \phi(0)) = 0$

Proof:

Given that $y' = A(x) \cdot y$ and ϕ is a FM of $\textcircled{1}$.

We know that $y(x) = \phi(x) \cdot c$ is also a soln of ①.

We know that y is periodic

$$\Leftrightarrow y(\omega) = y(0)$$

$$\Leftrightarrow \phi(\omega) \cdot c = \phi(0) \cdot c$$

$$\Leftrightarrow (\phi(\omega) - \phi(0)) \cdot c = 0$$

$$\Leftrightarrow \det(\phi(\omega) - \phi(0)) = 0 \quad \text{for non-trivial } \omega.$$

Theorem:

Let the matrix $A(x)$ be continuous and periodic with period $\omega \in \mathbb{R}$. Let $\phi(x)$ be the FM of the system

$$y' = A(x)y + B(x) \quad \text{--- ①}$$

Then ① has a unique periodic solution of period ω ,

\Leftrightarrow the system $y' = A(x)y$ does not have a periodic soln of period ω .

Proof

Given that ϕ is a FM of $y' = A(x)y$. Let $x_0 = 0$. We have the solution of ① as

$$y(x) = c \cdot \phi(x) + \phi(x) \int_0^x \phi^{-1}(t) \cdot B(t) \cdot dt,$$

c is some coefficient.

y is periodic $\Leftrightarrow y(\omega) = y(0)$.

$$\Rightarrow c \cdot \phi(\omega) = c \cdot \phi(0) + \phi(\omega) \int_0^\omega \phi^{-1}(t) \cdot B(t) \cdot dt$$

$$\Rightarrow (\phi(\omega) - \phi(0))c = \phi(\omega) \int_0^\omega \phi^{-1}(t) \cdot B(t) \cdot dt$$

This has a non-trivial soln

$$\Leftrightarrow \det(\phi(\omega) - \phi(0)) \neq 0.$$

$\Leftrightarrow y' = A(x)y$ does not have a periodic soln.

Floquet's theorem

Let the matrix $A(x)$ be continuous and periodic with period $\omega \in \mathbb{R}$. Then the following hold.

i) The matrix $\psi(x) = \phi(x + \omega)$ is also a FM of the system, $y' = A(x)y$.

ii) There exists a periodic non-singular matrix $P(x)$ of period ω and a constant matrix R such that

$$\phi(x) = P(x) \cdot e^{Rx}$$

Result:

Let A be a non-singular matrix. Then there exist a matrix B such that

$$A = e^B$$

Lect - 7, Mar 23

Boon's birthday!

Floquet's theorem

1. $\phi(x + \omega)$ is a FM

2. $\phi = P \cdot e^{Rx}$, P is periodic and R is const.

Proof:

ii) Given that ϕ is a FM of $y' = Ay$.

to prove that $\psi(x) = \phi(x + \omega)$ is a FM.

$$\begin{aligned} \text{Consider } \psi'(x) &= \phi'(x + \omega) = A(x + \omega) \cdot \phi(x + \omega) \\ &= A(x) \cdot \phi(x) \end{aligned}$$

$\Rightarrow \psi$ is a soln of $y' = A(x)y$.

$$\det(\psi(x)) = \det(\phi(x + \omega)) \neq 0$$

$\Rightarrow \psi$ is a FM of $y' = Ay$

(ii) We know that $\phi(x)$ and $\phi(x+\omega)$ are

FM of $y' = Ay$.

We also know that any soln. can be of the form $\phi(x) \cdot C$, where C is non-singular, i.e.,

$$\phi(x+\omega) = C \cdot \phi(x)$$

$$\text{Let } P(x) = \phi(x) \cdot e^{-Rx}$$

$$\text{Since } C \text{ is non-singular, } C = e^{R\omega}$$

Claim: P is periodic

to prove that, $P(x+\omega) = P(x)$.

$$\begin{aligned} \text{Consider, } P(x+\omega) &= \phi(x+\omega) \cdot e^{-R(x+\omega)} \\ &= \phi(x) \cdot C \cdot e^{-Rx} \cdot e^{-R\omega} \\ &= \phi(x) \cdot e^{R\omega} \cdot e^{-Rx} \cdot e^{-R\omega} \\ &= \phi(x) \cdot e^{-Rx} \\ &= P(x) \end{aligned}$$

$\Rightarrow P$ is periodic.

$$P = \phi \cdot e^{-Rx}$$

$$\Rightarrow \phi = P \cdot e^{Rx}$$

Reduction of a periodic system to a system with constant coefficient.

Theorem:

Let $P(x)$ and R be the matrices as in Floquet's theorem. Then the transformation, $y(x) = P(x) \cdot v(x)$

reduces the differential system $y' = A(x) \cdot y$ to $v' = Rv$ with constant coeff. matrix R .

Proof:

We know that ϕ is a FM of

$$y' = A(x) \cdot y \quad \text{--- (1)}$$

By Floquet's theorem we have,

$$\phi = P \cdot e^{Rx}$$

ϕ is a solution of (1) $\Rightarrow A' = A \cdot \phi$.

$$\Rightarrow (P e^{Rx})' = A (P e^{Rx})$$

$$\Rightarrow P' e^{Rx} + P e^{Rx} \cdot R = A P e^{Rx}$$

$$\Rightarrow e^{Rx} (P' + PR - AP) = 0$$

$$\Rightarrow P' + PR - AP = 0$$

$$P' - AP = -PR \quad \text{--- (2)}$$

Consider $y = Pv$.

$$\therefore y' = Ay$$

$$\Rightarrow (Pv)' = A(Pv)$$

$$\Rightarrow P'v + Pv' = APv$$

$$\Rightarrow (P' - AP)v + Pv' = 0$$

$$\Rightarrow -PRv + Pv' = 0 \quad \left\{ \text{from (2)} \right.$$

$$\Rightarrow v' - Rv = 0 \quad \left. \left\{ P \text{ is non-singular} \right\} \right.$$

$$\Rightarrow v' = Rv$$

Asymptotic behaviour of linear systems

Theorem:

Let all the solution of the differential system, $y' = Ay$, $y(x_0) = y_0$, A is a constant matrix be bounded. Then all the solutions of perturbed system,

$$y' = (A + B(x)) \cdot y,$$

$B(x)$ is an $n \times n$ matrix continuous elements by $1 \leq i, j \leq n$ in the interval $[x_0, \infty)$, will be bounded, provided

$$\int_{x_0}^{\infty} \|B(t)\| \cdot dt < \infty.$$

Proof:

We have $y' = Ay$ is constant. $y(x_0) = y_0$.

①

We know that solution of ① is of the form e^{Ax} . It is given that soln. of ① is bounded.

$\Rightarrow \exists$ some constant c , such that

$$\|e^{Ax}\| \leq c$$

We have the perturbed system,

$$y' = (A + B(x))y \quad \text{--- ②}$$

The solution of ② is,

$$y(x) = e^{(x-x_0)A} \cdot y_0 + e^{xA} \int_{x_0}^x e^{-At} \cdot B(t) y(t) dt$$
$$= e^{(x-x_0)A} \cdot y_0 + \int_{x_0}^x e^{(x-t)A} \cdot B(t) y(t) dt$$

$$\|y(x)\| \leq c_0 + c \int_{x_0}^x \|B(t)\| \cdot |y(t)| dt$$

By Grönwall inequality,

$$|y(x)| \leq c_0 e^{\int_{x_0}^x \|B(t)\| dt}$$
$$\leq K \quad \because \int_{x_0}^x \|B(t)\| dt < \infty$$

Theorem:

Let all the soln of the differential system $y' = A(x)y$, $y(x_0) = y_0$ be bounded in $[x_0, \infty)$ and the condition,

$$\int_{x_0}^{\infty} \|B(t)\| dt < \infty$$

be satisfied, then all the soln of the perturbed system,

$$y' = (A(x) + B(x))y.$$

are bounded in $[x_0, \infty)$, provided

$$\lim_{n \rightarrow \infty} \inf \int_{x_0}^x \text{Tr}(A(t)) dt > -\infty$$

$$\text{or, } \text{Tr}(A(x)) = 0.$$

Proof:

We know that ϕ is the FM soln of $y' = A(x)y$.

$$\phi^{-1} = \frac{\text{Adj}(\phi)}{\det(\phi)}$$

$$= \frac{\text{Adj}(\phi)}{\det(\phi) \cdot \exp\left(\int_{x_0}^x \text{Tr}(A(t)) dt\right)}$$

Then both ϕ and ϕ^{-1} are bounded

{ since soln is bdd and due to given cond. }

Let,

$$c = \max \left\{ \sup \|\phi\|, \sup \|\phi^{-1}\| \right\}$$

We have the perturbed system,

$$y' = (A(x) + B(x))y \quad \text{--- ③}$$

$$y(x) = \phi(x) \cdot c + \phi \int_{x_0}^x \phi^{-1} B(t) y(t) dt$$

$$= \phi(x) \cdot \phi^{-1}(x_0) \cdot y_0 + \int_{x_0}^x \phi(t) \cdot \phi^{-1}(t) \cdot B(t) y(t) dt$$

$$|y(x)| \leq c_0 + c^2 \int_{x_0}^x \|B(t)\| \cdot |y(t)| dt$$

By CrI,

$$\Rightarrow |y| \leq c_0 \cdot \exp \left\{ c^2 \int_{x_0}^x \|B(t)\| dt \right\} \leq K.$$

Missed a few lectures:

\rightarrow 25 - Mar

\rightarrow 26 - Mar

Attached J's at the end. Sorry. You can ignore my notes from here and scroll to hers at the end.

Lect -n, Mar 20

Proposition:

Let all the roots of the characteristic eqn of

$$L(y) = y^{(n)} + a_1 y^{(n-1)} + \dots + a_n y = 0$$

where a_i 's are some constants, have negative real parts and let $\epsilon > 0$ be such that $-\epsilon > \max_{i \leq j \leq n} \text{real}(e^{\lambda_j})$ where

$\lambda_1, \lambda_2, \dots, \lambda_m$ are distinct roots. Then there

exists a constant k such that $|y(x)| \leq k e^{-\epsilon x}$, $x \geq 0$.

Proof:

We have $y^{(n)} + a_1 y^{(n-1)} + \dots + a_n y = 0 \implies \textcircled{1}$

Then, ch. eq of $\textcircled{1}$ is,

$$\lambda^n + a_1 \lambda^{n-1} + \dots + a_n \lambda = 0.$$

Suppose $\lambda_1, \lambda_2, \dots, \lambda_m$ be the roots with multiplicity q_1, \dots, q_m s.t. $q_1 + q_2 + \dots + q_m = n$.

Let $\lambda_j = \alpha_j + i \beta_j$, $j = 1, \dots, m$, $\alpha_j < 0$.

Let $y_j(x) = x^p e^{\lambda_j x}$, $0 \leq p < q_j$, $j = 1, \dots, m$.

consider

$$y_j(x) e^{\epsilon x} = x^p e^{\lambda_j x} e^{\epsilon x} = x^p e^{(\lambda_j + i \beta_j)x} e^{\epsilon x}$$

Note: $\alpha_j + \epsilon < 0$

$$|y_j(x) e^{\epsilon x}| = |x^p \cdot e^{(\alpha_j + \epsilon)x}|$$

\exists a k_j such that

$$|y_j(x) e^{\epsilon x}| \leq k_j$$

$$\Rightarrow |y_j(x)| \leq k_j \cdot e^{-\epsilon x}$$

We know that $y(x) = \sum c_i y_i(x)$

$$|y(x)| = \sum c_i |y_i(x)|$$

$$\leq \max c_i \sum |y_i(x)|$$

$$|y(x)| \leq \max c_i \sum k_j e^{-\epsilon x} \leq k e^{-\epsilon x}$$

Theorem:

1. Every solution $y = \phi(x)$ of $y' = Ay$ is stable of all the eigenvalue of A have neg. real part.
2. Every solution $y = \phi(x)$ of $y' = Ay$ is unstable if atleast one eigenvalue of A has the real part.

Proof:

We have $y' = Ay \implies \textcircled{1}$

We know that any solution $\psi(x)$ of $\textcircled{1}$ is

$$\psi(x) = e^{xA} \psi(0).$$

Let ϕ_{ij} be the i - j th component of e^{xA} .

Then,

$$\psi_i(x) = \sum_{j=1}^n \phi_{ij} \psi_j(0), \quad i = 1, \dots, n.$$

Let us assume that the eigenvalues of A has negative real part. Let $-\alpha_i$ be the largest negative real part of such eigen value.

Then, $\exists \epsilon$ such that $-\alpha_i - \epsilon < 0$

By the preims (??) proposition, $\exists k > 0$ s.t.

$$|\phi_{ij}(x)| \leq k e^{-\epsilon x}$$

Define $\|\psi(x)\| = \max \{ |\psi_j(x)|, j = 1, \dots, n \}$

$$\begin{aligned} \|\psi(x)\| &= \max |\psi_j(x)| \\ &= \max \left| \sum_{i=1}^n \phi_{ij}(x) \cdot \psi_i(0) \right| \end{aligned}$$

$$\begin{aligned} &\leq \max \left| \sum_{i=1}^n k \cdot e^{-\epsilon x} \cdot \psi_i(0) \right| \\ &= nk \|\psi(0)\| \end{aligned}$$

$$\leq nk \delta, \quad \|\psi(0)\| < \delta$$

$$< \epsilon, \quad \text{if chose } \delta = \frac{\epsilon}{nk}$$

i.e., $\|\psi(x)\| < \epsilon$ when $\|\psi(0)\| < \delta$.

Any solution $\psi(x)$ sufficiently close to the equilibrium point at $x = 0$ remains close to it infinite times as well.

\Rightarrow the soln is stable.

Proof:

Let λ be any positive eigen value of A .
Then

$$\psi(x) = ce^{\lambda x} \cdot v$$

when v is the eigenvalue.

$$\|\psi(x)\| = \|ce^{\lambda x} \cdot v\| \rightarrow \infty, \quad x \rightarrow \infty.$$

\Rightarrow the soln is unstable.

① $y' = Ay$ when $A = \begin{pmatrix} 1 & 5 \\ 8 & 1 \end{pmatrix}$ is unstable.

② Determine whether each solution $y(x)$ of

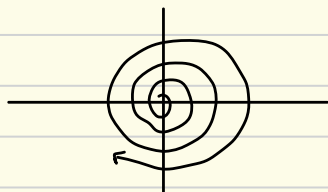
$$y' = Ay \quad \text{when} \quad A = \begin{bmatrix} -1 & 0 & 0 \\ -2 & -1 & 2 \\ -3 & -2 & -1 \end{bmatrix}$$

Lect - n+1, Apr - 1

Limit Cycle:

$$\left. \begin{array}{l} y_1' = f_1(x, y) \\ y_2' = f_2(x, y) \end{array} \right\} \text{--- } \textcircled{1}$$

A closed trajectory of the differential syst. $\textcircled{1}$, which is approached specifically either from inside or from outside by a non-closed trajectory of $\textcircled{1}$ as $x \rightarrow \infty$ or $x \rightarrow -\infty$ is called a limit cycle.



Poincare-Bendixson Theorem

Suppose that a solution $y(x) = (y_1(x), y_2(x))$ of the differential system $y_1' = f_1(x, y), y_2' = f_2(x, y)$ remains in a bounded region of y_1 - y_2 plane which contains no critical or equilibrium points of $\textcircled{1}$, then its trajectory must spiral into a simple closed curve which itself is the trajectory of a periodic solution.

Lecture incomplete.

Missed lectures:

\rightarrow 2 - Apr

\rightarrow 6 - Apr

Added J's handwritten notes after this.
Sorry!

25/3/26 Stability of the solution:

$$y' = f(x, y)$$

$$y(x_0) = y_0, \quad \tilde{y}(x_0) = y_0 + \Delta y_0 \quad \text{①}$$

Let $y(x) = y(x, x_0, y_0)$ be the solⁿ wrt i.c. $y(x_0) = y_0$

$\tilde{y} = y(x, x_0, y_0 + \Delta y_0)$ be the solⁿ wrt i.c. $\tilde{y}(x_0) = y_0 + \Delta y_0$

we say that solⁿ of $y(x)$ of ① is stable if given $\epsilon > 0$, $\exists \delta > 0$ ($\delta = \delta(\epsilon, x_0)$) s.t. $|\Delta y_0| < \delta \Rightarrow |y(x, x_0, y_0 + \Delta y_0) - y(x, x_0, y_0)| < \epsilon$.

$$\Rightarrow |y - \tilde{y}| < \epsilon$$

→ (Lyapunov's stability)

The solⁿ is asymptotically stable if it is stable and $|y(x, x_0, y_0 + \Delta y_0) - y(x, x_0, y_0)| \rightarrow 0$ as $x \rightarrow \infty$ when $|\Delta y_0| < \delta$.

↳ $y' = ay, y(x_0) = y_0$
 $\Rightarrow y(x) = e^{ax} y_0$

$$\tilde{y} = y(x, x_0, y_0 + \Delta y_0) = e^{ax} (y_0 + \Delta y_0)$$

$$|\tilde{y} - y| = |e^{ax} \Delta y_0| < \epsilon \text{ if } a < 0$$

→ Thm: the sol^s of the diff sys $y' = A(x)y$ are stable \Leftrightarrow they are bdd.

Pf Given that $y' = A(x)y \rightarrow ①$
 (⇒) Let ϕ be FM of ①, wkt any solⁿ $y(x)$ of ① is $y(x) = \phi(x)c = \phi(x)\phi^{-1}(x_0)y_0$.

Suppose that solⁿ is bdd $\Rightarrow \exists a < 0$ s.t. $|\phi(x)| < e^{ax}$

TPP: solⁿ is stable.

→ Consider $|y(x, x_0, y_0 + \Delta y_0) - y(x, x_0, y_0)|$

$$= |\phi(x)\phi^{-1}(x_0)(y_0 + \Delta y_0) - \phi(x)\phi^{-1}(x_0)y_0|$$

$$= |\phi(x)\phi^{-1}(x_0)\Delta y_0|$$

$$\leq c|\phi^{-1}(x_0)| |\Delta y_0|$$

$$\leq c|\phi^{-1}(x_0)| \delta$$

$$< \epsilon \text{ if } \delta = \frac{\epsilon}{c|\phi^{-1}(x_0)|} \Rightarrow \text{The solⁿ is stable}$$

(⇐) Conversely, suppose that the solⁿ is stable and we have tpt the solⁿ is bdd.

$$\text{solⁿ stable} \Rightarrow |y(x, x_0, y_0 + \Delta y_0) - y(x, x_0, y_0)| < \epsilon$$

$$\Rightarrow |\phi(x)\phi^{-1}(x_0)\Delta y_0| < \epsilon \quad \text{when } |\Delta y_0| < \delta$$

$$\Rightarrow |\phi(x)| |\phi^{-1}(x_0)| |\Delta y_0| < \epsilon$$

$$\Rightarrow |\phi(x)| < c \text{ where } c = \epsilon / \delta |\phi^{-1}(x_0)|$$

\Rightarrow solⁿ is bdd

• Thm: Let $\phi(x)$ be the FM of $y' = A(x)y$. Then, all solⁿs of diff sys are asymptotically stable $\Leftrightarrow \|\phi(x)\| \rightarrow 0$ as $x \rightarrow \infty$.

Pl: Given that ϕ is the FM of $y' = A(x)y$
 (\Rightarrow) Suppose $\|\phi(x)\| \rightarrow 0$ as $x \rightarrow \infty$ and ϕ is cont. Then, \exists const c s.t.
 $\|\phi(x)\| \leq c \Rightarrow$ r.h.s. bdd.
 \Rightarrow by prev thm, solⁿ is stable.

Consider, $\|y(x, x_0, y_0 + \Delta y_0) - y(x, x_0, y_0)\|$
 $= \|\phi(x) \phi^{-1}(x_0) \Delta y_0\|$
 $= \|\phi(x)\| \|\phi^{-1}(x_0) \Delta y_0\| \rightarrow 0$ as $x \rightarrow \infty$

Thus, solⁿ is asymptotically stable.

(\Leftarrow) conv, suppose solⁿ is asymptotically stable.
 IFT $\|\phi(x)\| \rightarrow 0$ as $x \rightarrow \infty$

AS $\Rightarrow \|y(x, x_0, y_0 + \Delta y_0) - y(x, x_0, y_0)\| \rightarrow 0$ as $x \rightarrow \infty$
 $\Rightarrow \|\phi(x) \phi^{-1}(x_0) \Delta y_0\| \rightarrow 0$ as $x \rightarrow \infty$
 $\Rightarrow \|\phi(x)\| \|\phi^{-1}(x_0) \Delta y_0\| \rightarrow 0$ as $x \rightarrow \infty$
 $\Rightarrow \|\phi(x)\| \rightarrow 0$ as $x \rightarrow \infty$. P2

• Autonomous system: $y' = f(x, y)$

$y' = A(x)y + B(x)$

If it depends on x , then it is called non-autonomous sys and if A does not depend on x (i.e., A is const matrix), then it is known as autonomous sys.

If $B = 0$, then it is called homogeneous sys, & if $B \neq 0$, then it is non-hom. autonomous sys. $y' = Ay$ A : constant matrix.

$y' = f(x, y)$
 $y' = f(y) \leftarrow y' = Ay$

suppose $A = \text{diag}(\lambda_1, \dots, \lambda_n)$
 we have $y(x) = e^{(x-x_0)A} y_0$
 $\begin{cases} y' = Ay \\ y(x_0) = y_0 \end{cases}$

$y(x) = \text{diag}(e^{\lambda_1(x-x_0)}, e^{\lambda_2(x-x_0)}, \dots, e^{\lambda_n(x-x_0)}) y_0$

$y' = Ay$
 $y = (y_1, \dots, y_n)$

y_i 's are known as the phases of the sys.

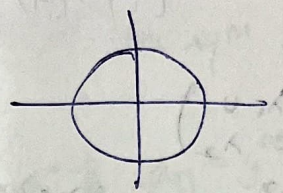
$\{y(x) \in \mathbb{R}^n\}$ is the trajectory or orbit of sys

\mathbb{R}^n : phase space and when $n=2, 3$ is called as phase-plane of sys.

$$\left[\begin{array}{l} y' = Ay \rightarrow y' = By \\ \text{red. to diag sys. \& solve} \end{array} \right] \text{Resp } \overline{AP}$$

26/3/26
Ex?

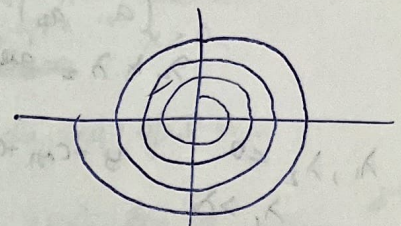
$$\begin{aligned} y' &= Ay \\ y_1' &= -y_2 & y_2' &= y_1 \\ y_1'' &= -y_2' = -y_1 \Rightarrow y_1'' + y_1 = 0 \\ y_1 &= \cos t & y_2 &= \sin t \end{aligned}$$



Ex?

$$\begin{aligned} y_1' &= -y_1 - y_2 \\ y_2' &= y_1 - y_2 \\ y_1'' &= -y_1' - y_2' \\ &= -y_1' - (y_1 - y_2) \\ &= -y_1' - y_1 + (-y_1' + y_2) \\ &= -2y_1' - y_1 + y_2 \end{aligned}$$

$$\begin{aligned} y_1'' + 2y_1' - 2y_2 &= 0 \\ m &= -1 \pm i \\ y_1 &= e^{-t} \cos t \\ y_2 &= e^{-t} \sin t \end{aligned}$$



→ Eq^m points: $y' = Ay$, $y' = f(y)$
 We say that \bar{y} is an equilibrium pt of $y' = f(y)$ [$y' = Ay$] if $f(\bar{y}) = 0$.
 ↳ It is aka critical pt / singular point $y(x) = \bar{y}$ is a solⁿ of $y' = Ay$ if \bar{y} is an equilibrium point.

$$y' = Ay, \det(A) \neq 0$$

then $y=0$ is an eq^m pt; in fact, $y=0$ is the unique eq^m pt.

helps us to analyze stab. of solⁿ.

↳ It is aka steady state solⁿ.

→ To find the eq^m point:

Solve for $f(\bar{y}) = 0$

(Q.) Find all eq^m points of sys:

$$(i) \frac{dy_1}{dx} = 1 - y_2 \quad \frac{dy_2}{dx} = y_1 + y_2$$

$$f(y) = \begin{pmatrix} 1 - y_2 \\ y_1 + y_2 \end{pmatrix} \cdot \text{Let } \bar{y} \text{ be eq^m pt}$$

$$\Rightarrow f(\bar{y}) = 0 \Rightarrow \begin{cases} 1 - \bar{y}_2 = 0 \\ \bar{y}_1 + \bar{y}_2 = 0 \end{cases}$$

$$\bar{y}_2 = 1 \quad \bar{y}_1 = -1$$

∴ $\begin{pmatrix} -1 \\ 1 \end{pmatrix}$ is the eq^m pt

(ii) $y' = (y_1 - 1)(y_2 - 1)$, $y' = -(y_1 + 1)(y_2 + 1)$

$f(y) = 0 \Rightarrow (\bar{y}_1 - 1)(\bar{y}_2 - 1) = 0 \Rightarrow \bar{y}_1 = 1 \text{ or } \bar{y}_2 = 1$
 $(\bar{y}_1 + 1)(\bar{y}_2 + 1) = 0 \Rightarrow \bar{y}_1 = -1 \text{ or } \bar{y}_2 = -1$

$(-1), (1)$ are eq^m pts of sys

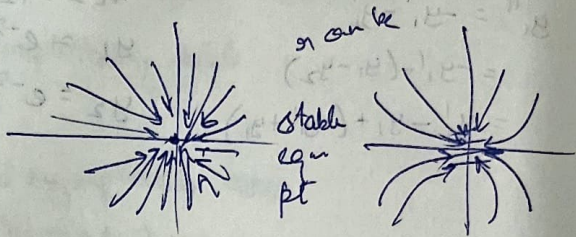
$\rightarrow y' = Ay$, $A = \begin{pmatrix} \lambda_1 & 0 \\ 0 & \lambda_2 \end{pmatrix}$

$y_1(x) = e^{\lambda_1 x} v_1$, $y_2(x) = e^{\lambda_2 x} v_2$

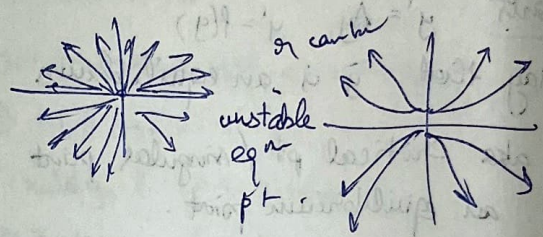
$A = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}$, $|A - \lambda I| = 0$

λ_1 & λ_2 are roots of ch. poly.

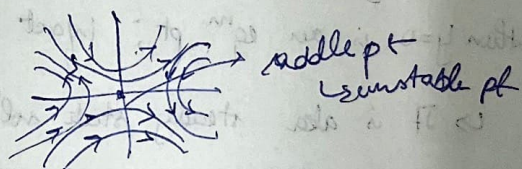
$\rightarrow \lambda_1, \lambda_2 < 0$ $y = c_1 y_1 + c_2 y_2$
 $\lambda_1 > \lambda_2$
 $y_1(x) \rightarrow 0$, $y_2(x) \rightarrow 0$ as $x \rightarrow \infty$



\rightarrow when λ_1 & $\lambda_2 > 0$,
 $y_1(x) \rightarrow \infty$, $y_2(x) \rightarrow \infty$ as $x \rightarrow \infty$



\rightarrow one +ve, one -ve.
 $\frac{y_1}{y_2} = e^{(\lambda_2 - \lambda_1)x} \frac{c_1}{c_2}$, $\lambda_2 < 0, \lambda_1 > 0$.



Stability of an autonomous system:

Consider $y' = Ay \rightarrow \textcircled{1}$. Let $\phi(x)$ be a solⁿ of $\textcircled{1}$.

\rightarrow The solⁿ $y = \phi(x)$ is said to be stable if every solⁿ $\psi(x)$ of $\textcircled{1}$ starting sufficiently close to $\phi(x)$ at $x = 0$ must remain close to $\phi(x)$ in future time as well.

\rightarrow If at least one of the solⁿ $\psi(x)$ sufficiently close to $\phi(x)$ at $x = 0$ deviates away from $\phi(x)$ as $x \rightarrow \infty$, then we say that ϕ is unstable.

\rightarrow In other words, stability means given $\epsilon > 0$, $\exists \delta > 0$ st $|\phi_j(x) - \psi_j(x)| < \epsilon$ whenever $|\phi_j(0) - \psi_j(0)| < \delta$, $j = 1, \dots, n$.

\rightarrow Show: Every solⁿ $y = \phi(x)$ of $y' = Ay$ is stable if the eq^m solⁿ is stable.

Prf: Let $y(x) = 0$ be the eq^m solⁿ of $y' = Ay \rightarrow \textcircled{1}$.
 Let ϕ and ψ be solⁿ of $\textcircled{1}$. Let $z(x) = \phi - \psi$, z is also a solⁿ of $\textcircled{1}$.
 Given $y(x) = 0$ is stable.

→ $\Sigma(x)$ close to $\phi(x)$ at $x=0$ remains close to it in future as well
 ⇒ $\phi(x)$ close to $\psi(x)$ at $x=0$ and remains close to $\psi(x)$ at future time as well

→ The solⁿ is stable.

Thm: A solⁿ $y = \phi(x)$ of $y' = Ay$ is unstable if the eqⁿ solⁿ is unstable.
 Pf: per.

Prop: Let all the roots of the char eqⁿ of $Ay' = y^{(m)} + a_1 y^{(m-1)} + \dots + a_m y = 0$, where a_i 's are some constts, have negative real parts and let $\beta > 0$ be s.t. $-\beta > \max_{1 \leq j \leq m} \text{Re}(\lambda_j)$ where $\lambda_1, \dots, \lambda_m$ are distinct roots. Then, \exists constt k s.t. $|y(x)| \leq k e^{-\beta x}$, $x \geq 0$.

Pf: We have $y^{(m)} + a_1 y^{(m-1)} + \dots + a_m y = 0$. The char. eqⁿ of \mathcal{D} is:
 $\lambda^m + a_1 \lambda^{m-1} + \dots + a_m = 0$

Suppose $\lambda_1, \dots, \lambda_m$ be the roots with multiplicities q_1, \dots, q_m s.t.
 $q_1 + \dots + q_m = m$.

Let $\lambda_j = \alpha_j + i\beta_j$ $j=1, \dots, m$, $\alpha_j < 0$

Let $y_j(x) = x^p e^{\lambda_j x}$ $0 \leq p < q_j$, $j=1, \dots, m$.

Consider $y_j(x) e^{\beta x} = x^p e^{(\alpha_j + i\beta_j)x} e^{\beta x} = x^p e^{(\alpha_j + \beta)x} e^{i\beta_j x}$

Note that $\alpha_j + \beta < 0$.
 $|y_j(x) e^{\beta x}| = |x^p e^{(\alpha_j + \beta)x}| \leq k_j$ s.t.

$$\Rightarrow |y_j(x)| \leq k_j e^{-\beta x}$$

wkt

$$\begin{aligned} y(x) &= \sum c_i y_i(x) \\ |y(x)| &= \sum c_i |y_i(x)| \\ &\leq \max c_i \sum |y_i(x)| \\ &\leq \max c_i \sum k_j e^{-\beta x} \\ &\leq k e^{-\beta x} \end{aligned}$$

(2)

Thm: (i) Every solⁿ $y = \phi(x)$ of $y' = Ay$ is stable if all e -vals have negative real part.
 (ii) Every solⁿ $y = \phi(x)$ of $y' = Ay$ is unstable if atleast one e -val of A has +ve real part.

Pf: We have $y' = Ay \rightarrow \mathcal{D}$.

wkt any solⁿ $\phi(x)$ of \mathcal{D} is $\phi(x) = e^{xA} \phi(0)$.

Let ϕ_{ij} be the i -th component of e^{xA} , then $\phi_i(x) = \sum_{j=1}^n \phi_{ij} \phi_j(0)$
 $i=1, \dots, n$.

Pf: (i) Let us assume that the e-val of A has \neq real part. Let $-\alpha_1$ be the largest \neq real part of such e-val.

Then, $\exists \beta$ s.t. $-\alpha_1 < -\beta < 0$.

By the prev prop, $\exists k > 0$ s.t. $|\phi_j(x)| \leq k e^{-\beta x}$.

Define $\|\psi(x)\| = \max \{ |\phi_j(x)|, j=1, \dots, n \}$.

$$\begin{aligned} \|\psi(x)\| &= \max |\phi_j(x)| \\ &= \max \left| \sum_{j=1}^n \phi_{ij}(x) \phi_j(x) \right| \\ &\leq \max \left| \sum_{j=1}^n k e^{-\beta x} \phi_j(x) \right| \\ &= nk \|\psi(0)\| \\ &\leq nk \delta \quad \|\psi(0)\| < \delta \\ &< \varepsilon \quad \text{if we choose } \delta = \frac{\varepsilon}{nk} \end{aligned}$$

$$\Rightarrow \|\psi(x)\| < \varepsilon \text{ when } \|\psi(0)\| < \delta$$

\Rightarrow Any solⁿ $\psi(x)$ sufficiently close to eqⁿ pt at $x=0$ remains close to it in future as well
 \Rightarrow solⁿ is stable

(ii) Let λ be any \neq e-val of A .

Then $\psi(x) = c e^{\lambda x} v$, where v is e-vector.

$$\begin{aligned} \|\psi(x)\| &= \|c e^{\lambda x} v\| \rightarrow \infty \text{ as } x \rightarrow \infty \\ &\text{(regardless of val of } c) \\ \Rightarrow \text{solⁿ is } \underline{\text{unstable}} \quad \textcircled{Rd} \end{aligned}$$

(Q) (i) Show that every solⁿ of system $y' = Ay$, $A = \begin{pmatrix} 1.5 \\ 5 & -1 \end{pmatrix}$ is unstable

(ii) Determine whether each solⁿ $y(x)$ of $y' = Ay$, $A = \begin{pmatrix} -1 & 0 & 0 \\ -2 & -1 & -2 \\ -3 & -2 & -1 \end{pmatrix}$ is asymptotically stable or unstable.

$$\begin{aligned} \text{A) (i) } \begin{pmatrix} 1-\lambda & 5 \\ 5 & -1-\lambda \end{pmatrix} &= \lambda^2 - 2\lambda - 24 = 0 \\ \lambda &= \frac{2 \pm \sqrt{4+96}}{2} = \frac{2 \pm 10}{2} = 6, -4 \\ &\downarrow \\ &\text{+ve e-val (Re-part)} \\ &\Rightarrow \text{solⁿ } \underline{\text{unstable}} \end{aligned}$$

$$\text{(ii) } \begin{cases} (-1-\lambda)((-1-\lambda)^2 - (4)) = 0 \\ (-1-\lambda)(\lambda^2 + 2\lambda + 3) = 0 \end{cases}$$

$$\lambda = -1, -1 \pm 2i$$

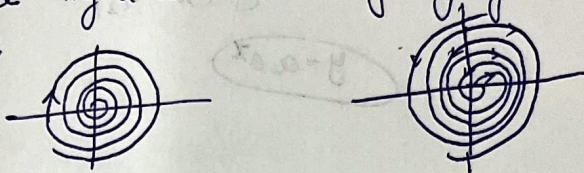
$$\begin{aligned} \lambda &= \frac{-2 \pm \sqrt{4+12}}{2} \\ &= \frac{-2 \pm 4}{2} \\ &= -3, 1 \end{aligned}$$

1/4/26

Limit Cycle:

$$\left. \begin{aligned} y_1' &= f_1(x, y) \\ y_2' &= f_2(x, y) \end{aligned} \right\} \textcircled{1}$$

A closed trajectory of the differential sys. $\textcircled{1}$ which is approached spirally either from inside or from outside by a non-closed trajectory of $\textcircled{1}$ as $x \rightarrow \infty$ or $x \rightarrow -\infty$ is called a limit cycle.



Poincaré - Bendixson Theorem:

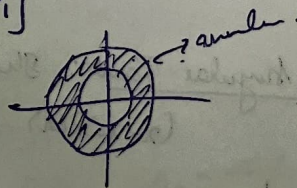
Suppose that a ~~soln~~ solution $y(x) = (y_1(x), y_2(x))$ of the diff sys $y_1' = f_1(x, y)$ remains in a bounded region of $y_1 - y_2$ plane which contains $y_2' = f_2(x, y)$ no critical/equ pt of $\textcircled{1}$. Then, its trajectory must spiral into a single closed curve which itself is the trajectory of a periodic solⁿ.

Ex: (i) $y'' + (2y^2 + 3y'^2 - 1)y' + y = 0$

Let $y_1 = y$
 $y_2 = y'$ } $y_1' = y_2$
 $y_2' = y_1'' = (1 - 2y_1^2 - 3y_2^2)y_2 - y_1$

$$y_2' = (1 - 2y_1^2 - 3y_2^2)y_2 - y_1$$

Consider $\frac{d(y_1^2 + y_2^2)}{dx} = 2y_1 y_1' + 2y_2 y_2'$
 $= 2y_1 y_2 + 2y_2 [(1 - 2y_1^2 - 3y_2^2)y_2 - y_1]$
 $= 2y_2 [1 - 2y_1^2 - 2y_2^2]$
 $\geq 0 \Rightarrow \frac{1}{3} < y_1^2 + y_2^2 < \frac{1}{2}$



Power series solⁿ for d.e.

$$\sum_{n=0}^{\infty} a_n x^n, \quad |n| < R \quad \text{for eqn}$$

Ratio test, $\lim_{n \rightarrow \infty} \left| \frac{a_{n+1}}{a_n} \right| < 1$
 $\text{for } \lim_{n \rightarrow \infty} \left| \frac{a_n}{a_{n+1}} \right| = R.$

Suppose $y = y$ \rightarrow $\textcircled{1}$
 Assume that $y = \sum a_n x^n$ is a solⁿ of $\textcircled{1}$

$$y = a_0 + a_1 x + a_2 x^2 + \dots$$

$$y' = a_1 + 2a_2 x + 3a_3 x^2 + \dots$$

from $\textcircled{1}$, $a_0 + a_1 x + a_2 x^2 + \dots = a_1 + 2a_2 x + 3a_3 x^2 + \dots$

$$\Rightarrow a_1 = a_0$$

$$\Rightarrow 2a_2 = a_1 = a_0 \Rightarrow a_2 = a_0/2$$

$$\Rightarrow 3a_3 = a_2 = a_0/2 \Rightarrow a_3 = a_0/3!$$

$$\therefore y = \frac{a_0}{0!} + \frac{a_0}{1!}x + \frac{a_0}{2!}x^2 + \frac{a_0}{3!}x^3 + \dots$$

$$= a_0 \left(1 + x + \frac{x^2}{2!} + \dots \right)$$

$$y = a_0 e^x$$

Ex: $y'' = 2xy$

Assume $y = \sum a_n x^n$ is solⁿ.

$$2x(a_0 + a_1x + a_2x^2 + \dots) = 2a_1 + 2a_2x + 2a_3x^2 + \dots$$

$$2a_0x + 2a_1x^2 + 2a_2x^3 + \dots = 2a_1 + 2a_2x + 2a_3x^2 + \dots$$

$$a_1 = 0$$

$$2a_0 = 2a_2 = 4a_0 \Rightarrow a_2 = a_0$$

$$2a_1 = 2a_3 = 0 \Rightarrow a_3 = 0$$

$$2a_2 = 4a_4 \Rightarrow a_4 = a_2/2 = a_0/2$$

...

$$y = a_0 \left(1 + \frac{x^2}{1!} + \frac{x^4}{2!} + \dots \right) e^{-x^2}$$

Ordinary & Singular points:

$$y'' + P(x)y' + Q(x)y = 0$$

P, Q are constⁿ at $x=x_0$. A pt $x=x_0$ is said to be ordinary pt / regular pt if P, Q are analytic at $x=x_0$

Regular Singular Point: The pt $x=x_0$ is said to be a regular singular point if $(x-x_0)P(x)$ & $(x-x_0)^2Q(x)$ are analytic at $x=x_0$.

\hookrightarrow if any one condⁿ is not satisfied, it is irregular singular pt.

(Q)

(i) $(1-x^2)y'' - 2xy' + p(p+1)y = 0$

(ii) $x^2y'' + a_1xy' + by = 0$

(iii) $x^2y'' + xy' + (x^2-n^2)y = 0$

(iv) $x^3(x-2)y'' + x^3y' + by = 0$

Ex (i) $y'' - \frac{2x}{1-x^2}y' + \frac{p(p+1)}{1-x^2}y = 0$

$$P = \frac{-2x}{1-x^2}$$

$$Q = \frac{p(p+1)}{1-x^2}$$

$x = \pm 1$: singular

others : ordinary

Take $x=1$: Consider $(x-1)P(x)$ & $(x-1)^2 Q(x)$

$$\Rightarrow (x-1) \frac{-2x}{(1-x)(1+x)} = \frac{2x}{1+x} \rightarrow \text{analytic at } x=1$$

$$\Rightarrow (x-1)^2 \frac{P(x+1)}{(1-x)^2} = -P(x+1) \frac{(1-x)}{(1+x)} \rightarrow \text{analytic at } x=1$$

$\rightarrow x=1$ is regular singular pt

Why

$x=1$ is a RSP.

(ii) $y'' + \frac{a}{x^2} y' + \frac{b}{x^2} y = 0$

$P(x) = a/x$ $Q = b/x^2$

$x=0$ regular, others: ordinary

Take $xP(x)$ & $x^2Q(x)$.

$\Rightarrow xP(x) = a \rightarrow$ analytic

$\Rightarrow x^2Q(x) = b \rightarrow$ analytic.

$\Rightarrow x=0$ is a RSP

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Thm: Let x_0 be an ordinary point of the d.e. $y'' + p(x)y' + q(x)y = 0 \rightarrow \textcircled{1}$

& let a_0 & a_1 be arbitrary constants. Then, $\exists!$ solution $y(x)$ that is analytic at x_0 is a solution of $\textcircled{1}$ in a certain neighborhood of x_0 satisfying the I.C. $y(x_0) = a_0$ and $y'(x_0) = a_1$. Furthermore, if the power series \exp^n of $P(x)$ & $Q(x)$ are valid on an interval $|x-x_0| < R$, then the power series \exp^n of the solⁿ is also valid in the same interval.

(No pf)

Ex: $y'' + y = 0 \rightarrow \textcircled{1}$

$P=0$ $Q=1$.

Let $y = \sum_{n=0}^{\infty} a_n x^n$ be a solⁿ of $\textcircled{1}$.

$y' = \sum_{n=1}^{\infty} n a_n x^{n-1}$

$y'' = \sum_{n=2}^{\infty} n(n-1) a_n x^{n-2} = \sum_{n=2}^{\infty} (n+1)(n+2) a_{n+2} x^n$

$\textcircled{1} \Rightarrow \sum_{n=2}^{\infty} (n+1)(n+2) a_{n+2} x^n + \sum_{n=0}^{\infty} a_n x^n = 0$

$\Rightarrow \sum_{n=0}^{\infty} [(n+1)(n+2) a_{n+2} + a_n] x^n = 0$

$\Rightarrow (n+1)(n+2) a_{n+2} + a_n = 0$

$\Rightarrow a_{n+2} = \frac{-a_n}{(n+1)(n+2)}$

$n=0$ $a_2 = -a_0/2$

$n=1$ $a_3 = -a_1/6$

$n=2$ $a_4 = \frac{-a_2}{4 \cdot 3} = \frac{a_0}{4!}$

$n=3$ $a_5 = \frac{-a_3}{4 \cdot 5} = -a_1/5!$

we have $y(x) = a_0 + a_1 x + a_2 x^2 + \dots$

$= a_0 \left(1 - \frac{x^2}{2!} + \frac{x^4}{4!} - \dots \right) + a_1 \left(x - \frac{x^3}{3!} + \frac{x^5}{5!} - \dots \right)$
 $= a_0 \cos x + a_1 \sin x$

Ex 2: Legendre eqⁿ: $(1-x^2)y'' - 2xy' + p(p+1)y = 0$, near $x=0$, p : const.

$$P(x) = \frac{-2x}{(1-x^2)} \quad Q(x) = \frac{p(p+1)}{(1-x^2)}$$

$P(x)$ & $Q(x)$ are analytic in nbd of $x=0$.

\therefore we have valid power series near $x=0$

Let $y = \sum_0^\infty a_n x^n$ be a solⁿ of ①

$$y' = \sum n a_n x^{n-1}$$

$$y'' = \sum n(n-1) a_n x^{n-2} \Rightarrow \sum (n+1)(n+2) a_{n+2} x^n$$

$$x^2 y'' = \sum n(n-1) a_n x^n$$

$$x y' = \sum n a_n x^n$$

① becomes,

$$\sum (n+1)(n+2) a_{n+2} - \sum n(n-1) a_n x^n - 2 \sum n a_n x^n + p(p+1) \sum a_n x^n = 0$$

$$\Rightarrow \sum [(n+1)(n+2) a_{n+2} - (n(n-1) + 2n - p(p+1)) a_n] x^n = 0$$

$$\Rightarrow (n+1)(n+2) a_{n+2} - (n^2 - p^2) a_n = 0$$

$$\rightarrow (n+1)(n+2) a_{n+2} = (n^2 - p^2) a_n$$

$$a_{n+2} = \frac{-(p-n)(p+n) a_n}{(n+1)(n+2)}$$

$$\underline{n=0} \quad a_2 = \frac{-p(p+1)}{1 \cdot 2} a_0$$

$$\underline{n=1} \quad a_3 = \frac{-(p-1)(p+2)}{2 \cdot 3} a_1$$

$$\underline{n=2} \quad a_4 = \frac{-(p-2)(p+3)}{3 \cdot 4} a_2 = \frac{p(p-2)(p+1)(p+3)}{4!} a_0$$

$$\underline{n=3} \quad a_5 = \frac{-(p-3)(p+4)}{4 \cdot 5} a_3 = \frac{(p+4)(p-3)(p+2)(p-1)}{5!} a_1$$

Thus,

$$y(x) = a_0 a_0(x) + a_1 a_1(x)$$

$$= a_0 \left[1 - \frac{p(p+1)}{2!} x^2 + \frac{p(p-2)(p+1)(p+3)}{4!} x^4 + \dots \right] + a_1 \left[x - \frac{(p-1)(p+2)}{3!} x^3 + \frac{(p-1)(p+2)(p-3)(p+4)}{5!} x^5 + \dots \right]$$

$$= a_0 y_1(x) + a_1 y_2(x)$$

$p \rightarrow$ even, y_1 finite

$p \rightarrow$ odd, y_2 finite.

(Q.3) $y'' + xy' + y = 0$.

(i) find $y_1 = a_0 + a_1x + a_2x^2$ as power series

(ii) Show that $y_1(x)$ is series \exp^m of $e^{-x^2/2}$ & use this fact to find a second solⁿ $y_2(x)$.

Exercise

Power series expⁿ of a RSP:

$x = x_0$ is RSP $\Rightarrow (x-x_0)P(x)$ & $(x-x_0)^2 Q(x)$ are analytic.

let $x_0 = 0$ for convenience $\Rightarrow xP(x)$ & $x^2Q(x)$ are analytic at $x=0$.

$\Rightarrow xP(x) = \sum p_n x^n$ & $x^2Q(x) = \sum q_n x^n$

$y = x^m \sum a_n x^n = \sum a_n x^{n+m}$.

where m is the solⁿ of $m(m-1) + mp_0 + q_0 = 0$ is known as the indicial eqⁿ.

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\hookrightarrow aka Frobenius Series solⁿ Method.

Thm - (Frobenius series solⁿ for DE with RSP) $\rightarrow \textcircled{1}$

Let $x=0$ be a RSP of DE $y'' + P(x)y' + Q(x)y = 0$ and that the power series $xP(x) = \sum p_n x^n$ & $x^2Q(x) = \sum q_n x^n$ are valid in the interval $|x| < R$, $R > 0$. Let the indicial eqⁿ $m(m-1) + mp_0 + q_0 = 0$ have real roots m_1 & m_2 with $m_2 < m_1$. Then, $\textcircled{1}$ has atleast one solⁿ $y_1(x) = x^{m_1} \sum a_n x^n$, $a_0 \neq 0$ on the interval $0 < x < R$, where a_n 's are determined i.t.o a_0 by the recurrence relⁿ

$a_n [(m_1+n)(m_1+n-1) + (m_1+n)p_0 + q_0] + \sum_{k=0}^{n-1} a_k [(m_1+k)p_{n-k} + q_{n-k}] = 0 \rightarrow \textcircled{2}$

with m replaced by m_1 & series $\sum a_n x^n$ cgs for $|x| < R$. Furthermore, if $m_1 - m_2 \neq 0$ or $m_1 - m_2 > 0 \in \mathbb{Z}^+$, then $\textcircled{1}$ has a second independent solution

$y_2(x) = x^{m_2} \sum a_n x^n$, $a_0 \neq 0$. On the same interval, where a_n 's are determined from

$\textcircled{2}$ i.t.o a_0 with m replaced m_2 & series cgs for $|x| < R$.

When $m_1 - m_2 = 0$ or an integer, the second solution can be found by computing

$y_2 = v y_1$ where $v' = \frac{1}{y_1} e^{-\int p dx}$ and the solⁿ will be of form $y_2(x) = y_1(x) \ln x + \sum a_n x^n$

(Q) $2x^2 y'' + x(2x+1)y' - y = 0$: find indicial eqⁿ & its roots.

$y'' + \frac{x(2x+1)}{2x^2} y' - \frac{y}{2x^2} = 0$

$P(x) = \frac{x(2x+1)}{2x^2} = 1 + \frac{1}{2x}$ $Q(x) = -\frac{1}{2x^2}$

$x=0$ is a singular pt,

$xP(x) = x + \frac{1}{2}$
 $x^2Q(x) = -\frac{1}{2}$ $\Rightarrow x=0$ is a RSP & $p_0 = \frac{1}{2}$ & $q_0 = -\frac{1}{2}$

∴ The indicial eqⁿ is $m(m-1) + m p_0 + q_0 = 0 \Rightarrow m(m-1) + \frac{1}{2}m - \frac{1}{2} = 0$

$$\Rightarrow 2m(m-1) + m - 1 = 0$$

$$\Rightarrow (m-1)(2m+1) = 0$$

$$\boxed{m = -\frac{1}{2}, 1}$$

(Q1) Find two independent Frobenius series solⁿ of

(i) or $y'' + 2y' + xy = 0$

(ii) $x^2 y'' - x^2 y' + (x^2 - 2x)y = 0$

(Q2) Find a Frobenius series solⁿ of $x^2 y'' + xy' + x^2 y = 0$
($m_1 = m_2$)

(Q.1.A) (i) $xy'' + 2y' + xy = 0$

$$\Rightarrow y'' + \frac{2}{x}y' + y = 0$$

$\alpha = 0$ is regular, $P = \frac{2}{x}$ $Q = 1$

$\alpha P(x) = 2$, $\alpha^2 Q(x) = x^2 \Rightarrow \alpha = 0$ is RSP

$p_0 = 2$ $q_0 = 0$

indicial eqⁿ

$$m(m-1) + 2m + 0 = 0 \Rightarrow m(m-1+2) = 0$$

$$\Rightarrow m = 0, -1$$

Let $y = \sum a_n x^{m+n}$ is a solⁿ of de $y' = \sum (m+n)a_n x^{m+n-1}$

$$y'' = \sum (m+n)(m+n-1)a_n x^{m+n-2}$$

$$xy'' = \sum (m+n)(m+n-1)a_n x^{m+n-1}$$

$$2y' = \sum 2a_n x^{m+n}$$

$$\sum [(m+n)(m+n-1)a_{n+1} + 2(m+n+1)a_{n+1} + a_{n-1}] x^{m+n} = 0$$

$$(m+n+1)(m+n+2)a_{n+1} = -a_{n-1}$$

$$a_{n+1} = \frac{-a_{n-1}}{(m+n+1)(m+n+2)}$$

when $m=0$,

$$a_{n+1} = \frac{-a_{n-1}}{(n+1)(n+2)} \rightarrow \text{1st solⁿ}$$

$m = -1$

$$a_{n+1} = \frac{-a_{n-1}}{n(n+1)} \rightarrow \text{2nd solⁿ}$$

→ Note, for equal roots, to get 2 indep solⁿ,
 one solⁿ (y_1) will be obtained by the method
 for other root,

$$y_2(x) = y_1 \log x + \sum a_n x^n$$

$$y_2 = v y_1, \quad v = \int \frac{1}{y_1^2} e^{-\int p dx} dx$$

$$n p(x) = \sum p_n x^n$$

$$p(x) = \frac{p_0}{x} + p_1 + p_2 x + \dots$$

$$e^{-\int p dx} = e^{-\left[\int \frac{p_0}{x} + p_1 + p_2 x + \dots\right]}$$

$$= e^{-\left[p_0 \log x + p_1 x + \frac{p_2 x^2}{2} + \dots\right]}$$

$$= x^{-p_0} e^{-\left[p_1 x + \frac{p_2 x^2}{2} + \dots\right]}$$

$$= x^{-p_0} e^{-[p_1 x + \dots]}$$

$$v = \int \frac{1}{\left(\sum a_n x^n\right)^2} dx = \int \frac{1}{x^{m_1 - p_0} \left(\sum a_n x^n\right)^2} e^{-[p_1 x + \dots]} dx$$

Legendre Eqⁿ:

$$(1-x^2)y'' - 2xy' + p(p+1)y = 0$$

$$a_{n+2} = \frac{-(p-n)(p+n)}{(n+1)(n+2)} a_n$$

$y = a_0 y_1 + a_1 y_2 \rightarrow$ one or other, other finite deg poly.

↳ The Legendre poly $P_n(x)$ (of deg n) is the solⁿ of the Legendre eqⁿ satisfying

$$P_n(1) = 1$$

→ Rodrigues formula for Legendre Poly:

The Legendre poly $P_n(x)$ is given by

$$P_n(x) = \frac{1}{2^n n!} \frac{d^n}{dx^n} (x^2-1)^n$$